MODEL

SR9628@160 SR9628@500



| Typical field of view ¹ near mid far | 118 130 142 mm | 295 310 328 mm |
|---|-----------------------|-----------------------|
| Measurement range 1 | 60 mm | 140 mm |
| Stand-off distance | 160 mm | 500 mm |
| Typical vertical resolution (Z) 1 | 6.5 - 9 μm | 46 - 56 μm |
| Typical lateral resolution (Y) 1 | 92 - 110 μm | 225 - 310μm |
| Z-Linearity ^{2,5} | 0.008% (4.8 μm/mm) | 0.025% (35 μm/mm) |
| Z-Repeatability 4,5 | 1.4 μm | 6 μm |
| Weight | Approx. 1900 g | Approx. 1900 g |
| Part number (laser class 2M 3B) | 3.003.001 3.003.002 | 3.003.025 3.003.026 |

| Maximum points / 3D profile | 1272 | |
|------------------------------------|--|--|
| Typical scan rate ³ | Approx. from 2.5 kHz up to 25 kHz | |
| Typical 3D point rate ³ | Approx. from 3.2 up to 32 million points/sec | |
| Interface | Gigabit Ethernet (1 Gbit/sec) | |
| Inputs | 4 x Inputs, 5 - 24 VDC | |
| | Quadrature Encoder (AB-Channel, RS-422 standard) | |
| Outputs | 2 x Outputs, 24 VDC (max. 20 mA) | |
| Trigger | START Trigger support on Input 1 | |
| | DATA Trigger support on Quadrature Encoder Input (Max. DATA trigger rate: 100 kHz) | |
| | DATA Trigger support on Input 2, 3 (Max. DATA trigger rate: 10 kHz) | |
| Input voltage Power | 24 VDC, ± 15% ripple 13 W | |
| Laser wavelength | 660 nm | |
| Laser class standard optional | 2M 3B | |
| Maximum ambient light | 10,000 lx | |
| EMC test | as per EN 61 000-6-2, EN 61 000-6-4 | |
| Vibration / Shock test | as per EN 60 068-2-6, -27, -29, -64 | |
| Electrical safety | as per EN 61 010-1-3 | |
| Protection class | III, as per EN 61 040-3 | |
| Enclosure rating | IP65 | |
| Air humidity | Maximum 90%, non-condensing | |
| Temperature operation storage | 0 - 40° C -20 - 70° C | |
| Compatible accessories | Power-I/O cable: 6.310.0XX | |
| | Ethernet cable: 6.302.0XX | |
| | Encoder cable: 6.307.0XX | |
| | | |

Typical values can vary up to 5% due to optical tolerances
Z-Linearity calculated as variation of "bias" (reference value vs. measured value) over the measurement range. The %slope of a best-fit line from a plot of bias over measurement range represents Z-Linearity
Scan rate & point rate are dependent on the configured field of view, measurement range and exposure time. The typical scan/point rate has been estimated with an exposure time of 1 µsec
Experimentally assessed by scanning a measurement target moving over a conveyor belt 50 times. Measurement performed by averaging height values within the Z-Map image. No post-processing filters applied
Measurements performed on a SmartRay standard artifact which is an aluminum flat surface painted matte white



